

### **MEGGITT** smart engineering for extreme environments

# VibroSmart<sup>®</sup> DMS vibration monitoring module

#### FEATURES

- VibroSight® compatible hardware from the Vibro-Meter® product line
- 2 individually configurable dynamic input channels with up to 19 kHz bandwidth
- >> 1 auxiliary input channel, including tachometer
- >> Synchronous sampling of input channels
- >> Up to 20 configurable processed outputs per module
- Spectrum analyzer (FFT) up to 1600 lines every 1 s
- >> Up to 4 alarms per processed output, with hysteresis and time delay
- AND, OR and majority voting logic functions for the combination of alarm and status information for a module
- Redundant communications and redundant power supply inputs to improve availability
- Analog outputs: 2 local outputs configurable as either 4-20 mA or ±5 V
- >> Discrete outputs: 2 local SPDT relays
- >> Real-time Ethernet communications
- Live insertion and removal of modules (hotswappable) with automatic reconfiguration
- >> Fully software configurable
- Robust enclosures with DIN rail mounting adaptor (on terminal base)

#### **APPLICATIONS**

Machinery protection and/or condition monitoring



VSV300 vibration monitoring module (with a VSB300 terminal base)



(Some certifications pending)



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### VSV300

#### DESCRIPTION

#### Introduction

The VibroSmart® distributed monitoring system (DMS) is a system of modular and scalable products designed for condition monitoring and machinery protection applications for power generation turbines, oil and gas applications and auxiliary balance-of-plant equipment.

VibroSmart DMS modules can be mounted directly on machinery, reducing the need for expensive cabling, because they are designed and certified to work in extremes, such as harsh industrial environments characterized by potentially explosive atmospheres (Ex Zone 2), high temperatures (70 °C) and high mechanical stress. VibroSmart complements the VM600 series of rack-based solutions from Meggitt Sensing Systems' Vibro-Meter® product line and is compatible with the same VibroSight® software.

The VibroSmart VSV300 vibration monitoring module has two independent dynamic vibration channels and one auxiliary channel, that can be configured as either a tachometer or a DC input channel. This measurement module is capable of stand-alone vibration monitoring or can be integrated with other VibroSmart DMS modules to create a larger system with more measurement channels and features.

#### VibroSmart DMS

A Meggitt Sensing Systems VibroSmart DMS is a network of small and economical modules (providing measurement, communications or other functions) that are connected together in measurement blocks in order to provide the functionality normally offered by rack-based machinery monitoring systems. A VibroSmart DMS consists of one or more measurement blocks, each containing up to 16 VibroSmart modules, a power supply and an optional host computer running the VibroSight software.

A measurement block is a logical grouping of VibroSmart modules that allows data such as tachometer, trigger and alarm information to be shared, for example, in order to monitor the same machine. Measurement blocks are configured using the VibroSight software.

Note: A VibroSmart DMS is limited to a maximum of 16 VSV300 modules per measurement block and a maximum of 8 measurement blocks without VibroSmart VSN010 real-time Ethernet switches. However, if each measurement block contains a VSN010, then a higher number of measurement blocks can be achieved, limited only by overall system performance (network traffic, VibroSight computer configuration and so on).

A VibroSmart DMS module consists of an electronics module (providing configurable machinery monitoring functions) that clips into a VibroSmart terminal base, which mounts on a DIN rail. A range of plug-in signal conditioners and plug-in communications interfaces that interface directly with VibroSmart modules will be available to provide an integrated solution for interfacing to sensors and fieldbuses.

VibroSmart terminal bases incorporate buses and connectors to provide all of the I/O connections required to interface to a VibroSmart module. Terminal bases also include non-volatile memory to store the configuration of the attached VibroSmart module, which allows modules to be hot-swapped. Modules and terminal bases use mechanical keycoding for a system that is simple to operate and use.

Different VibroSmart modules, terminal bases, plug-in signal conditioners and plug-in communications interfaces can be combined to offer unique combinations of functionality, versatility and safety assurance. In this way, a monitoring system can be built to meet the exact needs of an application resulting in a more cost-effective and reliable solution.

#### VSV300 vibration monitoring module

The VSV300 vibration monitoring module performs the data acquisition and all of the signal processing (filtering, analog-to-digital conversion, time and frequency domain processing, and resampling) required to produce processed outputs and extracted data for physical output and data presentation in VibroSight and VibroSight Scope. This includes spectral band extractions, advanced FFT analysis, trending and limit checks (alarm and sensor OK), and run-up / run-down acquisition.

In addition, the VSV300 module has 4 basic and 2 advanced logic functions that can be used to combine local alarm and status information in order to drive one of the VSV300 relays. This local information and the logic function outputs can also be used as inputs to the basic logic functions of a VSI010 communications interface module in the same measurement block.

Like all VibroSmart DMS modules, the VSV300 is fully software configurable using the VibroSight software. Using VibroSight Configurator, a module can be

#### **DESCRIPTION** (continued)

configured to capture data continuously at scheduled intervals or on the detection of an alarm condition. In addition, spectral resolution, frequency bandwidth, windowing function and averaging are all fully configurable. Using VibroSight Vision, a catalogue of static plots (including bar chart, bode, correlation, polar, shaft centerline, table and trend) and dynamic plots (including orbit, spectrogram, spectrum, full spectrum, waterfall/cascade, full waterfall/cascade and waveform) is available for the visualisation and analysis of measurement data.

#### Communications

All VibroSmart DMS modules and devices communicate using a system bus (SBUS), based on Ethernet technology, that supports data transfer rates of 100 Mbps at distances up to 100 m. The SBUS ensures the transfer of both non-real-time (standard) and real-time (time critical) information between VibroSmart modules, and supports communication with the host computer running the VibroSight software. The SBUS also communicates with the network time server that is recommended when the data logged by a VibroSmart DMS must be correlated with other system data, such as process data.

VibroSmart modules can either be located side-byside (adjacent to each other) or separate from one another. Such flexibility allows the functionality of a DMS to be physically distributed depending on the size of and access to the machinery being monitored. This helps reduce the expensive sensor cabling typically required between sensors and measurement modules, effectively replacing it with lower cost Ethernet and power supply cabling.

VibroSmart modules that are located side-by-side can communicate directly (no Ethernet cabling required) using the sidebus connectors on the terminal base that support both SBUS and redundant power supply distribution. VibroSmart modules that are mounted separate from one another can communicate over standard and redundant Ethernet networks of shielded twisted-pair Ethernet cable using the Ethernet connectors on the terminal base. However, using these Ethernet connectors does require that the power supply is distributed separately.

Discrete signal interface (DSI) inputs and tachometer signals can be connected directly to individual modules (locally). Alternatively, to reduce external wiring, these signals can be connected to a single VibroSmart module and shared among modules in the same measurement block using the SBUS.

#### Software

The VibroSight software platform, from Meggitt Sensing Systems, supports the configuration of the VibroSmart modules, data acquisition, data processing, data logging and data presentation. Many types of plots are available in VibroSight Vision to optimise the visualisation, analysis and interpretation of all live and historical measurement data.

VibroSight Scope is reduced functionality software with a simplified user interface that allows the presentation of static measurement data and status information being streamed live from VibroSmart modules.

#### **Applications information**

The VSV300 vibration monitoring module is ideal for monitoring, protecting, analysing and diagnosing critical assets such as gas turbines, steam turbines and other rotating machines. It can be used as a stand-alone module or as part of a more comprehensive monitoring system using the VibroSight software.

For specific applications, contact your nearest Meggitt Sensing Systems representative.

#### SPECIFICATIONS

Supported sensors	
Currently available	<ul> <li>Compatible with a range of sensors and signal conditioners using 2-wire current transmission and 3-wire voltage transmission</li> </ul>
Under development	: VibroSmart plug-in signal conditioners that interface directly with VibroSmart modules to provide a range of signal conditioning options
Dynamic input channels	
Number of independent channels	: 2
Measurement range	
• Voltage (AC+DC)	: ±3 or ±30 V <sub>PEAK</sub>
Current	: 15 or 150 mA
Frequency bandwidth (-0.1 dB)	: 0.1 Hz to 19 kHz
<ul> <li>Analog high-pass filter</li> </ul>	<ul> <li>An optional (software configurable) analog high-pass filter can be added to the AC path to configure the high-pass cutoff frequency (−3 dB) as 0.1, 1.0 or 3.0 Hz.</li> <li>This filter can also be disabled to allow DC-coupling of the input.</li> </ul>
Input impedance	
Voltage	: ≥100 kΩ, between the differential (high and low) inputs
Current	: 202 $\Omega \pm 3 \Omega$ , between the differential (high and low) inputs
Accuracy	
Amplitude	: ≤1% of input FSD (measurement bandwidth from 10 Hz to 1 kHz)
Phase	: ≤1° (measurement bandwidth from 10 Hz to 1 kHz)
Signal to noise ration (SNR)	: ≥80 dB (measurement bandwidth from 10 Hz to 2 kHz)
Common-mode voltage (CMV) range	: ±5 V
Common-mode rejection ratio (CMRR)	: >60 dB (at 50/60 Hz)
Crosstalk attenuation	: Typically 60 dB
Auxiliary input channel – used as a ta	ichometer input
Triggering method	: Crossing of threshold on rising edge of signal
Triggering threshold (rising edge)	· <sup>2</sup> / <sub>2</sub> of neak-neak value

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Voltage range	: ±30 $V_{RMS}$ / ±42.4 $V_{AC(PEAK)}$ or 60 $V_{DC}$

### For Ex Zone 2 applications, the voltage range must be $\leq$ 60 V<sub>PEAK-PEAK</sub>.

Tacho range (on input)	: 0.017 Hz to 426 kHz
Speed / frequency measurement range (after division by "number of teeth")	: 1 to 100000 RPM / 0.017 Hz to 1.667 kHz
Minimum input voltage for reliable detection	
Square-wave input signal	: 0.8 V <sub>РЕАК-РЕАК</sub> (0.017 Hz to 10 kHz) 2.0 V <sub>РЕАК-РЕАК</sub> (10 kHz to 427 kHz)
• Sinusoidal input signal	<ul> <li>20.0 V<sub>PEAK-PEAK</sub> (0.017 Hz to 0.1 Hz)</li> <li>10.0 V<sub>PEAK-PEAK</sub> (0.1 Hz to 1.0 Hz)</li> <li>2.0 V<sub>PEAK-PEAK</sub> (1.0 Hz to 20.0 Hz)</li> <li>0.8 V<sub>PEAK-PEAK</sub> (20.0 Hz to 10.0 kHz)</li> <li>2.0 V<sub>PEAK-PEAK</sub> (10.0 kHz to 426.4 kHz)</li> </ul>
Input impedance	
Voltage	: ≥110 k $\Omega$ , between the differential (high and low) inputs
Current	: 202 $\Omega$ ±3 $\Omega,$ between the differential (high and low) inputs



#### Auxiliary input channel – used as a DC input

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Measurement range		
• Voltage (DC)	: 0 to +20 V	
Current	: 0 to +100 mA	
Frequency bandwidth (−3 dB)	: DC to 10 Hz	
Input impedance		
Voltage	: ≥110 kΩ, between the differential (high and low) inputs	
Current	: 202 $\Omega$ ±3 $\Omega$ , between the differential (high and low) inputs	
Signal to noise ration (SNR)	: ≥72 dB	
Sensor OK check		
Range	: -20 to +20 VDC	
Operating principle		
Powered sensors	: DC voltage monitoring (open-circuit and short-circuit line check)	
Unpowered sensors	: Open-circuit line check only	
Digital signal processing		
A/D converter	: 24 bit	
Dynamic range	: ≥80 dB (from 10 Hz to 2 kHz)	
Frequency bandwidth	: 0 Hz to 19 kHz	

: ≤1% of input FSD

: 0.25 Hz to 10 kHz (main path)

Accuracy

Amplitude

Phase

Digital filtering

- High-pass filter cutoff frequency
- High-pass filter roll-off
- Low-pass filter cutoff frequency
- Low-pass filter roll-off Measurement resolution

FFT window

Averaging (frequency domain) Extracted data Extracted data type Integration count Qualifiers (rectifiers)

Order tracking VibroSight software update rate (external) -20 to -60 dB per octave
10 Hz to 19 kHz (main path)
-20 to -60 dB per octave

: ≤1.5° (measurement bandwidth from 10 Hz to 1 kHz)

- : 256 to 4096 point waveform / 100 to 1600 line spectrum
- : Flat top, Hamming, Hann (Hanning), Kaiser-Bessel with an alpha of 1, 5, 10, 20 or 25, Rectangular
- : Exponential averaging with up to 100 averages
- : Up to 20 processed outputs per module
- : Scalar, Vector, Phasor, Frequency line
- : 0, 1 or 2
- : True RMS, Scaled peak, Scaled peak-peak, Scaled average, True average, True peak, True peak-peak and Band peak
- : Digital resampling
- : 1 s max.

#### Single-channel processing blocks

Only one processing block can be assigned to an input channel at any one time. The number of processed outputs (data extractions) available depends on the processing block.

Asynchronous absolute bearing vibration (AAB)

Asynchronous absolute bearing vibration (Ar	
Main path     with band-pass filter	<ul> <li>Up to 3 outputs: one after the band-pass filter, one after the first integrator and one after the second integrator.</li> <li>Note: ISO 2954 compatible values can automatically be configured for the band-pass filter, if required.</li> </ul>
<ul> <li>Secondary path with low-pass filter</li> </ul>	: Spectrum (configurable averaging and integration) and up to 5 outputs. Waveform and up to 3 outputs.
Shaft relative vibration (RS)	
Main path     with separate AC and DC paths	<ul> <li>AC path with band-pass filter and up to 4 outputs.</li> <li>DC path with 1 output corresponding to the actual position of the shaft or target.</li> </ul>
Secondary path	: Spectrum (configurable averaging) and up to 8 outputs. Waveform.
Narrow-band vibration (NB)	
<ul> <li>With averaging and narrow band-pass filter</li> </ul>	<ul> <li>Spectrum (configurable averaging and integration) and up to 11 outputs. Waveform.</li> <li>Note: Narrow-band vibration (NB) is an order-tracked measurement and requires a tachometer input (1/rev) in order to track rotational speed.</li> </ul>
Tacho	
<ul> <li>With configurable "number of teeth" and "tacho ratio"</li> </ul>	: 1 output corresponding to the rotation speed of the shaft or target. Note: The tachometer input can be either the tachometer input of the module (local) or the tachometer input of a module in the same measurement block as the module (remote).
Position (PS)	
• <i>DC</i> path with offset (initial gap)	<ul> <li>DC path with 1 output corresponding to the actual position of the shaft or target.</li> <li>Notes: Position (PS) and shaft relative vibration (RS) processing blocks use the same signal processing functions to generate a position output.</li> <li>Position (PS) processing can be used with an auxiliary input channel configured as a DC input channel and with the dynamic Input channels.</li> </ul>
Broad-band pulsation (BBP)	
<ul> <li>Main path with band-pass filter and notch filter</li> </ul>	<ul> <li>Up to 2 outputs.</li> <li>Note: The notch filter can be configured as either 50 or 60 Hz to eliminate mains (power-line) frequency interference.</li> </ul>
<ul> <li>Secondary path with low-pass filter</li> </ul>	<ul> <li>Spectrum (configurable band rejection and averaging) and up to 5 outputs.</li> <li>Waveform and up to 3 outputs.</li> </ul>
Eccentricity (EC) – under development	
With low-pass filter	: Up to 2 outputs: continuous eccentricity (true peak-peak) and triggered eccentricity (peak-peak/rev) when a tachometer input is available. Note: the triggered eccentricity output requires that a tachometer input (1/rev) is available.
Quasi-static DC – under development	
• DC path with offset (initial value)	: DC path with 1 output corresponding to the measured physical quantity, such as a slowly varying process parameter.



#### **Dual-channel processing blocks**

<ul> <li>S<sub>max</sub></li> <li>Requires two shaft relative vibration (RS) processing blocks as inputs</li> </ul>	: 1 output corresponding to $S_{max}(t) = \sqrt{(X(t)^2 + Y(t)^2)}$
p	Note: ISO 7919-1 method C is used to calculate $S_{max}$ .
X-Ymax discriminator	
<ul> <li>Requires two shaft relative vibration (RS) processing blocks as inputs</li> </ul>	<ul> <li>1 output (true peak) corresponding to the higher of the two input signals.</li> <li>Note: ISO 7919-1 method B is used to calculate X-Ymax discriminator.</li> </ul>
Shaft absolute vibration (AS) – under develo	opment
<ul> <li>Requires one asynchronous absolute bearing vibration (AAB) processing block and one shaft relative vibration (RS) processing block as inputs</li> </ul>	<ul> <li>1 output corresponding to either:</li> <li>AS = AAB + RS with sensors at the same location, or</li> <li>AS = AAB - RS with sensors diametrically opposed.</li> </ul>
Alarm processing	
Alarms	: Four configurable alarm ranges (Danger+, Alert+, Alert-, Danger-) with configurable hysteresis and time delay
Adaptive monitoring	<ul> <li>Adaptive monitoring uses a control parameter (such as speed or position) to multiply the configured alarm limits by multiple coefficients configured for different ranges of the control parameter.</li> <li>Trip multiplier uses the DSI TM control signal to multiply the configured alarm limits by a single configurable coefficient.</li> </ul>
Alarm combination	
Logic functions	: AND, OR and majority voting logic, with optional inversion of individual inputs
Configurable functions	: Inversion of individual inputs
Basic logic functions	
Number	: 4
Configurable inputs	<ul> <li>From the sensor OK checks, and the measurement alarms (Danger+, Alert+, Alert-, Danger-) and associated data quality indicators (status bits) of the module</li> </ul>
Advanced logic functions	
Number	: 2
Configurable inputs	: From the basic logic function outputs of the module
Discrete signal interface (DSI) inputs Control signal	
• Alarm bypass (AB)	: A closed contact between the DSI AB and RET inputs inhibits the local relay outputs
• Alarm reset (AR)	: A closed contact between the DSI AR and RET inputs resets the alarms latched by the module
• Trip multiply (TM)	A closed contact between the DSI TM and RET inputs multiplies the alarm levels by a scale factor (software configurable), to enable trip multiplier-based adaptive monitoring
Operating principle	: Detection of an open circuit or a closed circuit on the input. These control signals can be connected directly to individual modules (locally) or connected to a single module (the DSI Master) and shared among modules in the same measurement block using the SBUS (remotely).

Buffered outputs – dynamic channels	
Туре	: Buffered transducer "raw" analog output
Number	: 2, available on J2 of the terminal base (see <b>Connectors on page 12</b> )
Frequency bandwidth	: 0 Hz to 19 kHz
Accuracy	
Amplitude	: ≤1% (measurement bandwidth from 0 Hz to 19 kHz)
Phase	: ≤1° (measurement bandwidth from 10 Hz to 10 kHz).
	<2° (measurement bandwidth from 10 kHz to 19 kHz).
Transfer ratios	
Voltage input	: 0.1 V/V (output-to-input ratio of 1:10, non-inverting)
Current input	: 20.2 mV/mA (non-inverting)
Admissible load on output	
Resistance	: ≥50 kΩ
Capacitance	: Able to drive up to 5 m of cable with a typical capacitance of 100 pF

Note: Where required, a VSA301 buffered output amplifier can be used to amplify the buffered transducer "raw" analog outputs, provide front-panel BNC connectors and allow the transmission of the signals over distances up to 500 m.

#### Buffered output - auxiliary channel

Туре	: Buffered transducer "raw" digital output. When the auxiliary channel is configured as a tachometer input, the buffered transducer "raw" output for the auxiliary channel is a process tachometer output. This buffered output is generated only when the tachometer is connected directly (locally) to the module.	
	no buffered output.	
Number	: 1, available on J2 of the terminal base (see <b>Connectors on page 12</b> )	
Voltage transfer ratio	: 0 to 5 V TTL-compatible signal (non-inverting)	
Admissible load on output		
Resistance	: ≥50 kΩ	
Capacitance	: Able to drive up to 5 m of cable with a typical capacitance of 100 pF	

Note: Where required, a VSA301 buffered output amplifier can be used to allow the transmission of the buffered transducer "raw" digital output (processed tachometer output) over distances up to 500 m.

#### Analog outputs

Number of local outputs	: 2 single-ended
Configurable as either	
• 4-20 mA (DC)	: Used to output a static signal (extracted data)
• ±5 V <sub>PEAK</sub> (AC)	: Used to output processed versions of a single dynamic channel signal or an arithmetic combination of both dynamic channel signals (simple addition or subtraction)
Admissible load on output (DC)	: ≤360 Ω
Admissible load on output (AC)	: ≥50 kΩ
Frequency bandwidth (AC)	:0 Hz to 10 kHz
Amplitude accuracy (AC)	:1% typ. (measurement bandwidth from 10 Hz to 2 kHz)
Number of additional (remote) 4-20 mA outputs	: Up to 6, using VSR0x0 relay modules (under development)



Discrete outputs	
Local relays	
Number	2
Configurable functions	Normally energized (NE) or normally de-energized (NDE). Latched or unlatched.
Configurable inputs	From the sensor OK checks, the measurement alarms (Danger+, Alert+, Alert-, Danger-) and the logic function outputs of the module
Number of additional (remote) relays	Up to 12, using VSR0x0 relay modules (under development)
Maximum switching voltage	$\pm$ ±30 V_{RMS} / ±42.4 V_{AC(PEAK)} or 60 V <sub>DC</sub>
For Ex Zone 2 applications, the voltag Table A.1 of EN 60079-11.	e and the current must be limited in accordance with
Relay characteristics	
Manufacturer	Panasonic
Type and contact arrangement	Single-pole double-throw (SPDT), with all contacts available on J3 of the terminal base (see <b>Connectors on page 12</b> )
Nominal switching capacity (resistive load)	0.5 A 125 V AC / 2 A 30 V DC
Maximum switching power (resistive load)	60 W (62.5 VA)
Maximum switching current	: 1 A <sub>AC</sub> / 2 A <sub>DC</sub>
Operate / release time	: 4 ms (max.) / 4 ms (max.)
Breakdown voltages	
Between open contacts	: 250 V <sub>AC</sub> (353 V <sub>PEAK</sub> )
<ul> <li>Between contact and coil</li> </ul>	: 250 V <sub>AC</sub> (353 V <sub>PEAK</sub> )
Mechanical / electrical life	10 <sup>8</sup> operations (min.) / 10 <sup>5</sup> operations (min.)
Environmental	
Operating	
Temperature	: −20 to +70°C (−4 to +158°F)
Humidity	0 to 90% non-condensing
Storage	Ũ
Temperature	: −40 to +85°C (−40 to +185°F)
Humidity	0 to 95% non-condensing
Protection rating	IP20 according to IEC 60529.
Ğ	It is also possible to deploy VibroSmart DMS modules and devices within an industrial housing in order to attain a rating of IP56.

Contact Meggitt Sensing Systems for more information.

For Ex Zone 2 applications, a protection rating of at least IP54 (or equivalent) is mandatory.

#### **Explosive atmospheres**

Available in Ex approved versions for use in hazardous locations

Type of protection Ex nA: non sparking		
Europe	EC type examination certificate	LCIE 13 ATEX 1041 X II 3 G (Zone 2) Ex nA IIC T6 T4 Gc
International	IECEx certificate of conformity	IECEx LCIE 13.0058X Ex nA IIC T6 T4 Gc
North America	CCSAUS certificate of compliance	cCSAus 70010491 Class I, Division 2, Groups A, B, C, D Ex nA IIC T6 Gc Class I, Zone 2 AEx nA IIC T6 Gc

Mhen using protection mode 'nA' (non-sparking), the user shall ensure that the vibration monitoring module is installed in an enclosure that ensures a protection rating of at least IP54 (or equivalent).

For specific parameters of the mode of protection concerned and special conditions for safe use, please refer to the Ex certificates that are available from Meggitt SA on demand.

#### Approvals

: CE marking
: IEC/EN 61010-1 Edition 3
: EN 61000-6-2 Edition 2.
EN 61000-6-4 Edition 2.
EN 61326-3-1 Edition 1.

#### Approvals (pending)

Hazardous area	: Ex (see Explosive atmospheres on page 10)
Other	: DNV GL (maritime) and GOST

#### SBUS communications (VibroSmart DMS)

Туре	: Real-time Ethernet
Network interface	: 100BASE-TX
Data transfer rate	: Up to 100 Mbps
Distance between devices	: Up to 100 m at 100 Mbps (100BASE-T compliant)
Network topologies	: Line and HSR ring
Number of modules	<ul> <li>: Up to 128 modules per VibroSmart DMS (without using VSN010 real- time Ethernet switches):</li> <li>• Up to 16 modules per measurement block (16 VSV300 modules max.)</li> <li>• Up to 8 measurement blocks per VibroSmart DMS.</li> </ul>
Signals shared across a measurement block	
Real-time	: Tachometric time-stamp, trigger and alarm messages
Non-real-time	: Remote DSI inputs. Measurement data (processed outputs and extracted data).



Note: SBUS is the system bus, based on real-time Ethernet, used by a VibroSmart DMS for all communications. The SBUS supports inter-module communication between VibroSmart modules such as the transfer of non-real-time information and real-time information such as tachometric time-stamps, triggers and alarms. The SBUS supports extra-module communications such as the exchange of commands, configuration information and measurement data between VibroSmart modules and a host computer running the VibroSight software, and communication between VibroSmart modules and a network time server.

Configuration	
VibroSmart modules	Fully software configurable over Ethernet, using a host computer running the VibroSight software
Terminal bases	<ul> <li>A DIP switch on the terminal base selects either the sidebus connector (J1x) or the Ethernet connector (Ethx) as the active SBUS port for each side of the terminal base.</li> <li>Only two physical ports can be active at any one time, that is, either J11 or Eth1 (right side) and either J10 or Eth2 (left side).</li> </ul>

#### **Time synchronisation**

Local synchronisation between VibroSmart devices (inter-module)

Protocol	: Precision time protocol (PTP)	
Accuracy	: <1 µs between VibroSmart modules in the same measurement block	
Required	: Yes (mandatory). For each measurement block, one module automatically acts as the PTP master for the other (slave) modules in the measurement block	
Global synchronisation between VibroSmart a	and other systems (extra-module)	
Protocol	: Network time protocol (NTP)	
Accuracy	: <10 ms between VibroSmart modules and an NTP server	
• Required	<ul> <li>No (optional).</li> <li>For a system, an NTP server can be manually configured as a common time reference in order to synchronise VibroSmart devices and a host computer and/or third-party systems, such as a DCS or PLC, for easy data correlation.</li> </ul>	
Power supply (input)	(124)( permised (140 to 120)( input region)	
Redundancy	: +24 $v_{DC}$ nominal (+16 to +32 $v_{DC}$ input range) : Two separate inputs for connection to different external power supplies	
Power supplies to sensors (outputs)		
Number of independent sensor power supplies	: 3 (one per input channel)	
Sensor power supply output		
<ul><li>Constant voltage</li><li>Constant current</li></ul>	: +24V <sub>DC</sub> ±3% (+25mA max.) <i>or</i> -24V <sub>DC</sub> ±3% (-25mA max.) : +6 mA ±1%	
Power consumption		
Total power consumption	: <8 W, with sensor power supplies enabled	



LED indicators		
Status	<ul> <li>Diag – indicates the status of the module, such as normal operation, configuration status or internal hardware or firmware failures.</li> <li>Network – indicates Ethernet link activity and status, and network time server synchronisation.</li> <li>Safety – indicates the status of the module's safety function and any active adaptive monitoring functions (AB or TM)</li> </ul>	
CH 1, CH 2 and AUX	<ul> <li>OK – indicates the status (sensor OK check) of the input signal for each channel.</li> <li>Alarm – indicates the status of each channel, such as normal operation and alarms (Danger+, Alert+, Alert-, Danger-).</li> </ul>	
Connectors		
J1 to J6	<ul> <li>10-pin terminal strip headers (male).</li> <li>Compatible with 10-pin BCF plug-in connectors (female) with PUSH IN spring connections having a clamping range from 0.14 to 1.5 mm<sup>2</sup> (26 to 16 AWG) and a recommended stripping length of 9 mm.</li> <li>See Recommendations for reliable connections on page 17.</li> </ul>	
• J1, bottom rear	: Redundant power supply inputs and local DSI inputs	
• J2, bottom centre	<ul> <li>Buffered version of raw input signals and analogue outputs configured for a processed output or extracted data</li> </ul>	
• J3, bottom front	: Local relay contacts (COM, NC and NO)	
• J4, top front	<ul> <li>Auxiliary input channel.</li> <li>Note: A VibroSmart plug-in signal conditioner or other external signal conditioner may be required.</li> </ul>	
• J5, top centre	<ul> <li>Dynamic input channel 2.</li> <li>Note: A VibroSmart plug-in signal conditioner or other external signal conditioner may be required.</li> </ul>	
• J6, top rear	<ul> <li>Dynamic input channel 1.</li> <li>Note: A VibroSmart plug-in signal conditioner or other external signal conditioner may be required.</li> </ul>	
J10, right side J11, left side	<ul> <li>Proprietary connectors.</li> <li>Sidebus connectors for SBUS communications (extra-module and inter-module) to a VibroSmart network and for the distribution of power to modules (redundant physical paths).</li> </ul>	
Eth1, bottom right Eth2, bottom left	<ul> <li>8P8C (RJ45) connectors, female.</li> <li>Ethernet connectors for SBUS communications (extra-module and inter-module) to a VibroSmart network.</li> <li>The Ethernet connectors (Ethx) are IEEE 802.3 Ethernet compatible with an isolation voltage of 1500 V<sub>RMS</sub>.</li> </ul>	



Physical	
Module mounting	: The VSV300 module clips into the VSB300 terminal base, which mounts on a TH 35-7.5 DIN rail.
Connection to other modules	<ul> <li>Sidebus connectors J10 and J11 allow direct connections between modules that are located side-by-side.</li> <li>Ethernet connectors Eth1 and Eth2 allow connections between modules mounted further apart, using twisted-pair Ethernet cable.</li> </ul>
Connection to a host computer	: Ethernet connectors Eth1 and Eth2 allow connections to a host computer or network, using twisted-pair Ethernet cable
Ethernet cabling	
Cable lengths (network segments)     less than 50 m	<ul> <li>Category 5 enhanced (Cat 5e) cable of type SF/UTP.</li> <li>A SF/UTP cable has overall (outer) screening using braided or foil shielding.</li> </ul>
• Cable lengths (network segments) up to 100 m	<ul> <li>Augmented category 6 (Cat 6a) or augmented category 7 (Cat 7a) cable of type S/FTP.</li> <li>A S/FTP cable has overall (outer) screening using braided shielding and individual pair shielding using foil.</li> </ul>
Connection to a sensor (front-end)	: Connector J4 is dedicated to the auxiliary input channel, while connectors J5 and J6 are dedicated to the dynamic input channels. See <b>Supported sensors on page 4</b> .
Connection to a power supply	: VibroSmart modules that are located side-by-side can distribute the power supply via the sidebus connectors J10 and J11 when at least one module is connected to the external +24 $V_{DC}$ supply. VibroSmart modules that are mounted separate from one another require that each module is connected to the external +24 $V_{DC}$ supply via its J1 connector.
Dimensions	
<ul><li>VSV300 module</li><li>VSB300 terminal base</li></ul>	See Mechanical drawings on page 14 See Mechanical drawings on page 14
Weight	
<ul><li>VSV300 module</li><li>VSB300 terminal base</li></ul>	: 300 g (0.66 lb) approx. : 550 g (1.21 lb) approx.



#### **MECHANICAL DRAWINGS**

#### VSV300 module - front view





Note: All dimensions are in mm (in) unless otherwise stated.



#### VSV300 module - other views







#### **MECHANICAL DRAWINGS** (continued)

#### VSB300 terminal base - front and rear views





Note: All dimensions are in mm (in) unless otherwise stated.

#### **MECHANICAL DRAWINGS** (continued)

#### VSB300 terminal base - side view



Note: All dimensions are in mm (in) unless otherwise stated.



#### **ORDERING INFORMATION**

To order please specify

Туре	Designation	Ordering number
VSV300	VibroSmart vibration monitoring module	600-008
VSB300	Terminal base for a VSV300 module	600-009

Notes:

The VSB300 is supplied with a set of 6x terminal base BCF plug-in connectors for J1 to J6 that are labelled and mechanically key-coded for the VSV300 / VSB300. Sets of additional connectors can be ordered as VSK002 (see **Accessories on page 17**).

#### ACCESSORIES

A number of accessories including connectors, plug-in signal conditioners (under development), DIN rails, cables and screws will be available to order.

Туре	Designation	Ordering number
VSA001	T30 Torx driver with a length of 150 mm (suitable for the DIN rail adaptor screw in terminal bases)	975.51.54.0030
VSA002	Cable assembly for use with the buffered outputs (J2) of a VSV300 module / VSB300, terminated with male BNC connectors for use as flying leads	934-129-000-011
VSA003	Cable assembly for use with the buffered outputs (J2) of a VSV300 module / VSB300, terminated with female BNC connectors for use with a patch panel	934-128-000-011
VSK002	Set of 6x terminal base BCF plug-in connectors for J1 to J6 (labelled and mechanically key-coded for a VSV300 / VSB300)	622-007-200-001

Notes:

The VSA002 is a 2 m cable assembly with a terminal base connector at one end for connection to the VSB300 terminal base (J2) and three male BNC connectors at the other end (one per output signal) for direct connections to test equipment.

The VSA003 is a 2 m cable assembly with a terminal base connector at one end for connection to the VSB300 terminal base (J2) and three female BNC connectors at the other end (one per output signal) for connections to BNC patch panels.

#### **RELATED PRODUCTS**

APF 19x APF 20x VSA002, VSA003, VSA004 and VSA005	AC-DC converters AC-DC converters with Ex approval BNC cable assemblies and patch panels	<ul><li>Refer to corresponding data sheets</li><li>Refer to corresponding data sheets</li><li>Refer to corresponding data sheet</li></ul>
VSA301 VSI010 VSN010	Buffered output amplifier Communications interface module Real-time Ethernet switch	<ul><li>Refer to corresponding data sheet</li><li>Refer to corresponding data sheet</li><li>Refer to corresponding data sheet</li></ul>

#### **RECOMMENDATIONS FOR RELIABLE CONNECTIONS**

It is highly recommended to terminate all wires connected to the BCF plug-in connectors (female) used by J1 to J6 of the VSB300 terminal base by crimping them with the appropriate industry standard wire-end ferrules, in order to help ensure consistent and reliable connections.

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Sales offices

#### Your local agent

#### Head office

Meggitt SA Route de Moncor 4

PO Box 1616 CH - 1701 Fribourg Switzerland

Tel: +41 26 407 11 11

Fax: +41 26 407 13 01

Meggitt Sensing Systems has offices in more than 30 countries. For a complete list, please visit our website.

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