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**Operating instructions No. 603 E**  
**FT 2000 Speed monitoring system**  
**Speed monitor FTFW 2022**

The speed monitor is a combination of a frequency relay and a frequency-current converter. It serves to measure and for monitoring a frequency proportional measured value (i.e. rpm).

The module is microprocessor-controlled and operates on the period measuring principle with subsequent computing of the reciprocal value (computing principle). The frequency is measured continuously. The number of cycles considered for a measurement period is dependent on the level of the input frequency and on the limits to be monitored.

After the input of a machine factor

$$M = f/n$$

with  $f(\text{Hz})$  = signal frequency of the sensor at  
 at a determined machine speed  
 and  $n (\text{rpm})$  = machine speed

the limits for the frequency relay and the measuring range for the frequency-current converter can be entered directly in rpm. For the limits, the switch-on point (limit high) and the switch-off point (limit low) can be put in separately, to permit the realisation of practically any hysteresis.

#### **Input of parameters**

The input or changing of all measuring parameters takes place via a separate handheld micro terminal FTM 2000, which can be plugged in to the front, with programming keys and a liquid crystal display. A matrix diagram (refer to drawing 4-110.664/1 allows a fast input of the parameters.

#### **Technical data:**

**Dimensions:** 19" rack mounting module, Europa card size

**Height:** 3 units = 132.5 mm

**Width:** 4 units = 20.32 mm

**Accuracy:** 0.2 % according to DIN/VDE 0410

**Resolution of the limit- and the measuring range input,**  
 referred to 100 % scale, better than 0.1 %.

**Temperature drift:** max. 150 ppm/°K (frequency measurement)  
 max. 300 ppm/°K (current output)

**Frequency range:** 0.05 Hz to 30 kHz

It can be exceeded for any duration up to 50 kHz without disturbing the function.

#### **Frequency input:**

**Sensor (S1), potential-free input, DC-coupled for rectangular pulses up to 30 kHz:**

V high > +10 Vp resp. I sink < 0.5 mA

V low < + 5 Vp resp. I sink > 5 mA

**Sensor power supply:** +12 V, 25 mA

**Dielectric strength** 500 V, 50 Hz against earth (front panel and rack).

Test (S2), potential-free input, DC-coupled for rectangular pulses up to 30 kHz:

V high > +10 Vp resp. I sink > 5 mA

V low < +1 Vp resp. I sink < 0.5 mA

Dielectric strength 500 V, 50 Hz against earth (front panel and rack).

An external frequency source may be electronically switched on the test frequency entry by means of a test key.

**Binary inputs:** (see drawing no. 4-110.714/1):

3 inputs (B1,B2,B3) for

- Startup bridging (the alarm triggered by the lowest limit is being suppressed for a startup time programmable from 0.0 to 999.9 s after short circuiting the binary input B1).
- Implicit sensor monitoring (sensor is ok when the lowest limit is exceeded, ie. the binary input B2 is short circuited to the negative pole via the relevant limit output, otherwise an alarm signal is activated).
- Startup monitoring (an alarm is activated during the startupbridging, when the lowest limit is NOT yet exceeded AND the binary input B3 is short circuited).

1 reset input

for the collective alarm and the limit outputs (after switching on the power or the triggering of an alarm due to the startup monitoring, the implicit sensor monitoring or the integrated microprocessor test, the rest input must be briefly short circuited to the negative pole).

The alarm triggering from the binary inputs can be delayed from 0.0 to 999.9 s.

The factory setting for the startup bridging is 10.0s and the alarm delay is 0.0 s. The delay time may be changed with the microterminal FTM 2000.

The corresponding time counter is being reset if the input state of an alarm function changes after the start of the delay time.

Binary inputs active low: I sink = 1 mA

Binary inputs high: U > + 3.5 V or open

**Binary outputs:**

8 limit outputs (G1...G8), open collector, switching to the negative pole, max. 100 mA, 3 V, short circuit-proof.

The function (limit mode) is "normal" or "inverse" and the status, limit status) is programmable "on" or "off":

- with "normal" and "on", exceeding the upper limit causes the corresponding output to be active low, i.e. low resistance, and falling below the lower limit renders the ouput high resistance.
- with "off" the corresponding limit output is always high resistance.

A green LED (LIMIT 1...8) on the front panel is on when the corresponding output is on low resistance. A collective alarm sets all eight limits on high resistance.

1 Relay output (K), 1 changing contact, max. 250 V, 1 A, 50 W. In case of inductive load, external spark suppression must be provided.

A collective alarm releases the relay.

The relay can additionally be freely assigned to the following state variables:

- limit 1
- limit 2
- etc.
- limit 8

The limit functions normal/inverse and on/off are also active here. With "normal" and "on" the exceeding of the upper limit is causing an attraction of the relay.

- failure (activated watchdog-timer OR broken fuse OR power failure)

A green LED (OK) on the front panel is on during normal operation.

The reaction time of the limit outputs is approx. 25 ms at an input frequency > 100 Hz.

The binary inputs and the open collector outputs have the negative pole of the supply voltage as a common reference potential.

**Current output:** Potential free (I+/I-)

0 to 20 or 4 to 20 mA by configuration, galvanic isolation.

Current at switching-on: 0 resp. 4 mA

Max. load: 500 Ohm (10 V/20 mA)

Open circuit voltage: 20 V

Resolution: 12 bit corresponding to 1/4096

Linearity error: max. 2 bit corresponding to 0.1 %

Setting time (deviation 1 % from nominal value):

20 ms at an input frequency of 0.1 Hz

30 ms at a frequency of = > 10 kHz

**Power Supply:** 18...33 V DC, typ. 1.8 W/max. 3 W.

The supply voltage is stabilised at +5 V with a regulator and if necessary transformed potential free by means of oscillation transformers.

**Protection against mains voltage failures:**

Mains voltage failure bridged up to 50 ms without malfunction.

**Interference immunity:**      Supply      Input and output  
   circuits      circuits

IEC 255-4	common mode:	2.5 kVs	2.8 kVs
	series mode:	1.0 kVs	--

IEC 801-4	common mode:	2.0 kVs	1.0 kVs
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**Ambient temperature:** 0...+60°C, + 70°C during max. 2 hours.

**Storage temperature:** -20...+85°C

Nov. 1992

# FT 2000

Anschlusschema  
Connection diagram  
Schéma de raccordement

## FTFW 2022

Drehzahlerfassung  
Speed monitor  
Moniteur de vitesse

**3732-03410**

**3732-03502 verdrahtet**

d b z

PS+	2	Hilfsenergie Pluspol (+) / Power supply plus terminal (+) /
PS-	4	Alimentation pôle positif (+)
PS-	4	Hilfsenergie Minuspol (-) / Power supply minus terminal (-) /
PS-	4	Alimentation pôle négatif (-)
PE	6	Schutzleiter / Protective Earth / Conducteur de protection

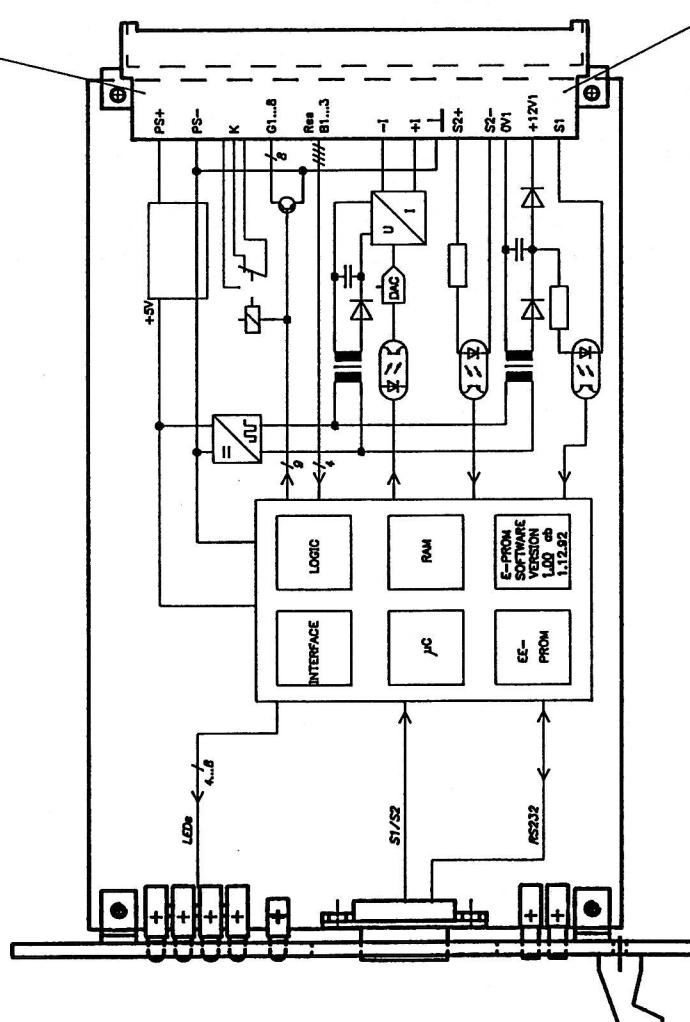


PE d b z 12 Schutzleiter / Protective Earth / Conducteur de protection

Res G8 G4	14	d Rücksetzeingang / Reset input / Entrée de mise à zero
	14	b Grenzwertausgang 8 / Limit output 8 / Sortie de limite 8
	14	b Grenzwertausgang 4 / Limit output 4 / Sortie de limite 4
B3 G7 G3	16	d Binäreingang 3 / Binary input 3 / Entrée binaire 3
	16	b Grenzwertausgang 3 / Limit output 3 / Sortie de limite 3
B2 G6 G2	18	d Binäreingang 2 / Binary input 2 / Entrée binaire 2
	18	b Grenzwertausgang 2 / Limit output 2 / Sortie de limite 2
B1 G5 G1	20	d Binäreingang 1 / Binary input 1 / Entrée binaire 1
	20	b Grenzwertausgang 1 / Limit output 5 / Sortie de limite 5
+!	22	d Analog Ausgang, Plus / Analog output, plus / Sortie analogique, plus
-!	22	d Analog Ausgang, Minus / Analog output, minus / Sortie analogique, moins
	24	d + -
S2+	26	d S2+ Testfrequenz / Test frequency / Fréquence de contrôle
S2-	26	d S2- Testfrequenz / Test frequency / Fréquence de contrôle

0 0 0 28	
0 0 0 30	d +12V1
0 0 0 32	d +12V1
0 0 0 32	d 0V1
0 0 0 32	d 0V1

F1 : 160 mA



Massbild:  
Dimensions: 3-110.544/2  
Côtes:

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Aenderungen: 5246 13.7.95 Wa./Ko.  
5132 17.12.95 STA.

Sach-Nr. 373



4-110.531/1

5246 13.7.95

12				
11	X=0Y=11 XYMODE MIN.FREQUENCY  .002Hz/.005Hz/.01Hz/.02Hz .05Hz/.1Hz/.2Hz/.5Hz/1Hz	X=1Y=11 XYMODE ALARM  latched/not latched	X=2Y=11 XYMODE NOT USED	X=3Y=11 XYMODE NOT USED
10	X=0Y=10 XYMODE CURRENT zero  8.888E+88	X=1Y=10 XYMODE CURRENT full  8.888E+88	X=2Y=10 XYMODE CURRENT output  0...20mA/4...20mA	X=3Y=10 XYMOD * CURRENT cal. ---- FEST VERBUNDEN MIT EINSCHUB  8888
09	X=0Y=09 XYMODE RELAY CONTROL  limit1/limit2/limit3/limit4 limit5/limit6/limit7/limit8 Alarm	X=1Y=09 XYMODE START DELAY  888.8s	X=2Y=09 XYMODE FAILURE DELAY  888.8s	X=3Y=09 XYMODE * SOFTWARE VERSION 1.00
08	X=0Y=08 XYMODE LIMIT 8 low  8.888E+88	X=1Y=08 XYMODE LIMIT 8 high  8.888E+88	X=2Y=08 XYMODE LIMIT 8 mode  Normal/Invers	X=3Y=08 XYMODE LIMIT 8 status  On/Off
07	X=0Y=07 XYMODE LIMIT 7 low  8.888E+88	X=1Y=07 XYMODE LIMIT 7 high  8.888E+88	X=2Y=07 XYMODE LIMIT 7 mode  Normal/Invers	X=3Y=07 XYMODE LIMIT 7 status  On/Off
06	X=0Y=06 XYMODE LIMIT 6 low  8.888E+88	X=1Y=06 XYMODE LIMIT 6 high  8.888E+88	X=2Y=06 XYMODE LIMIT 6 mode  Normal/Invers	X=3Y=06 XYMODE LIMIT 6 status  On/Off
05	X=0Y=05 XYMODE LIMIT 5 low  8.888E+88	X=1Y=05 XYMODE LIMIT 5 high  8.888E+88	X=2Y=05 XYMODE LIMIT 5 mode  Normal/Invers	X=3Y=05 XYMODE LIMIT 5 status  On/Off
04	X=0Y=04 XYMODE LIMIT 4 low  8.888E+88	X=1Y=04 XYMODE LIMIT 4 high  8.888E+88	X=2Y=04 XYMODE LIMIT 4 mode  Normal/Invers	X=3Y=04 XYMODE LIMIT 4 status  On/Off
03	X=0Y=03 XYMODE LIMIT 3 low  8.888E+88	X=1Y=03 XYMODE LIMIT 3 high  8.888E+88	X=2Y=03 XYMODE LIMIT 3 mode  Normal/Invers	X=3Y=03 XYMODE LIMIT 3 status  On/Off
02	X=0Y=02 XYMODE LIMIT 2 low  8.888E+88	X=1Y=02 XYMODE LIMIT 2 high  8.888E+88	X=2Y=02 XYMODE LIMIT 2 mode  Normal/Invers	X=3Y=02 XYMODE LIMIT 2 status  On/Off
01	X=0Y=01 XYMODE LIMIT 1 low  8.888E+88	X=1Y=01 XYMODE LIMIT 1 high  8.888E+88	X=2Y=01 XYMODE LIMIT 1 mode  Normal/Invers	X=3Y=01 XYMODE LIMIT 1 status  On/Off
00	X=0Y=00 XYMODE * FTFW 2022	X=1Y=00 XYMODE FIX TIME  0.01/0.03/0.07/0.15/0.30 0.50/1.20/2.40/4.80/9.60	X=2Y=00 XYMODE MACHINE FACTOR  8.888E+88	X=3Y=00 XYMODE STORE ?
Y X	Ø	1	2	3

